

Simplest stereo view of TEM images

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Abstract

In this short communication, the authors wish to remind an old but largely forgotten method of stereo view in TEM. It is possible to perceive TEM images stereoscopically without any technical equipment, which might facilitate the return of stereo methods in the active arsenal of electron microscopists.

1 During the last decades in Transmission Electron Microscopy (TEM),
2 significant efforts were made in 3D imaging of nanoscale objects [1]. For
3 example, electron tomography typically involves collection of a tilt series
4 consisting of 100 - 200 images followed by the reconstruction of a 3D object
5 with a variety of techniques. Tomography belongs to one of the most com-
6 plicated TEM methods demanding huge experimental efforts and intensive
7 image processing. Electron tomography is prone to be affected by numerous
8 instrumental and reconstruction issues, which stimulated the development of
9 a tremendous family of various technique modifications and reconstruction
10 algorithms to minimize artifacts.

11 In this communication, we would like to remind that a much simpler
12 method to retrieve the 3D arrangement of nanoscale objects might be suf-
13 ficient in many cases. Some higher animals (including humans) are capable
14 of *stereoscopic view*, i.e. ability to recognize essential features of 3D objects
15 from just two views taken under the slightly different perspectives of their
16 eyes. In the field of TEM, this ability would mean that just one moderate
17 tilt of an object in the microscope might provide sufficient information to
18 reconstruct at least some of its 3D geometry.

19 The idea of stereo TEM imaging is quite old. In fact, the implemen-
20 tation of a sample tilt in early electron microscopes of 20th century was

21 partially motivated by the wish to gain a stereo viewing facility [2], at that
22 time standard for light microscopy. TEM stereo imaging was quite common
23 in biology [3] but also found its niche in material science, for example in
24 studies of defects like dislocations [4] loops and voids formed in radiation
25 damage [2, 5] and for visualization of mesopores in zeolite [6]. In the closely
26 related area - Scanning Electron Microscopy (SEM), the stereoscopic meth-
27 ods were used as well [7]. However, the practical skills of stereo imaging
28 were largely lost [2] after the atomic-resolution paradigm became dominant
29 in TEM. The High-Resolution TEM (HRTEM) was very sensitive to small
30 tilts and, more importantly, the contrast formation in HRTEM appeared to
31 be hardly compatible with the perception mechanism hardwired in human
32 brains. Nevertheless, techniques of stereo imaging might be very useful for
33 medium resolution TEM work, which is still highly required in certain areas
34 like biology, mineralogy and environmental studies.

35 Fig.1 shows an example of a so-called stereo pair consisting of two images
36 of a 2D net composed of Au nanowires. The images were taken under a 14.4°
37 difference in α -tilt. In order to fit the human ability of stereo perception,
38 both images were rotated so that the direction of the α -tilt became horizontal.
39 Furthermore, the images were cropped to a circular shape as the arbitrary
40 tilted rectangular shapes might confuse the perception. Finally, we added
41 two sharp black fix points facilitating the fusion of both images into one
42 stereo view. The stereoscopic view allow to detect clearly the bending of the
43 2D network in different directions.

44 The key question is how to view such stereo pairs in order to achieve
45 3D perception. This often involve various equipment ranging from col-
46 ored/polarised glasses or binocular stereoviewers to assessors of virtual real-
47 ity. Those became recently quite common in gaming community but are still
48 rather an exception in research labs. Therefore, the necessity of any, even
49 simplest, devices hampers the broad spreading of stereo view practice among
50 electron microscopists.

51 In the present communication, we consider the techniques allowing to
52 perceive stereoscopic view *without* any technical equipment. Although a
53 certain initial training might be required, such ability would then allow for
54 stereo perception in any situations, just looking at a stereo pair at flat paper
55 or standard monitor. In the past, students of cartography were obliged to
56 practice such stereo view in order to perceive topographic stereo maps, but
57 in our days it is less common. The regular practicing of these techniques
58 could facilitate the return of stereo vision in the active arsenal of electron

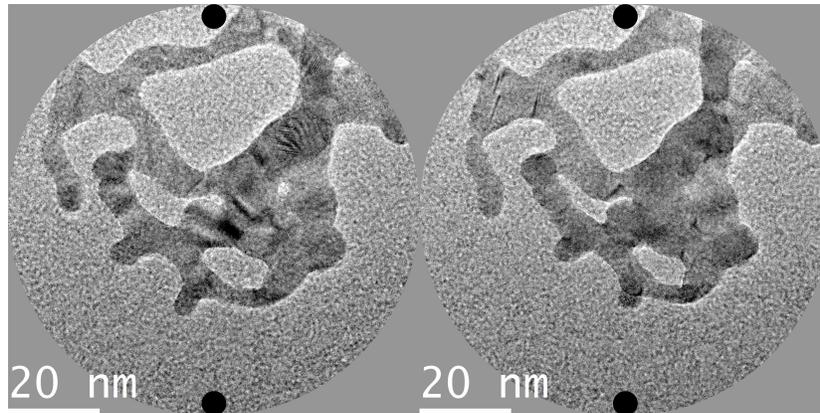


Figure 1: Stereo pair consisting of two images of Au networks, i.e a 2D net composed of Au nanowires. The images were taken under a 14.4° difference in α -tilt. To obtain stereo perception, it should be viewed with the divergence technique as shown in Fig. 2a. *Note that the physical width of the pair should not exceed 120 mm on paper or monitor for this viewing technique.* The same image can be viewed with the crossing technique (Fig. 2b) although the resulted 3D object will be mirrored in the depth dimension. The later technique allows to enlarge the physical size of the stereo pair to any desirable value.

59 microscopists.

60 The easiest way to perceive a 3D object from a stereo pair is to diverge
61 your view as shown in Fig. 2a:

- 62 1. Look normally at the stereo pair. Choose the distance between eyes
63 and the paper (monitor) most comfortable for viewing.
- 64 2. Try to glance "behind" the monitor. If this sounds not easy, place the
65 stereo pair near the monitor edge such as you can easily move your
66 view at some distant objects. The images perceived by the left and
67 right eyes start to split. One is moving to the left, another to the right.
- 68 3. Tune the appearance of two splitting images such as they form a kind
69 of a "trio" of images as shown in Fig. 2a. The marker points at the
70 upper and lower edges of the central image must coincide precisely. Tilt
71 the head a bit if necessary. Suddenly, your brain will start to perceive
72 the central image in the trio as a 3D object.

73 It is clear from Fig.2a that the divergence method put certain restrictions
74 on the physical size (on paper or on computer monitor) of a stereo pair. The
75 angle δ under which the observer normally inspects images is

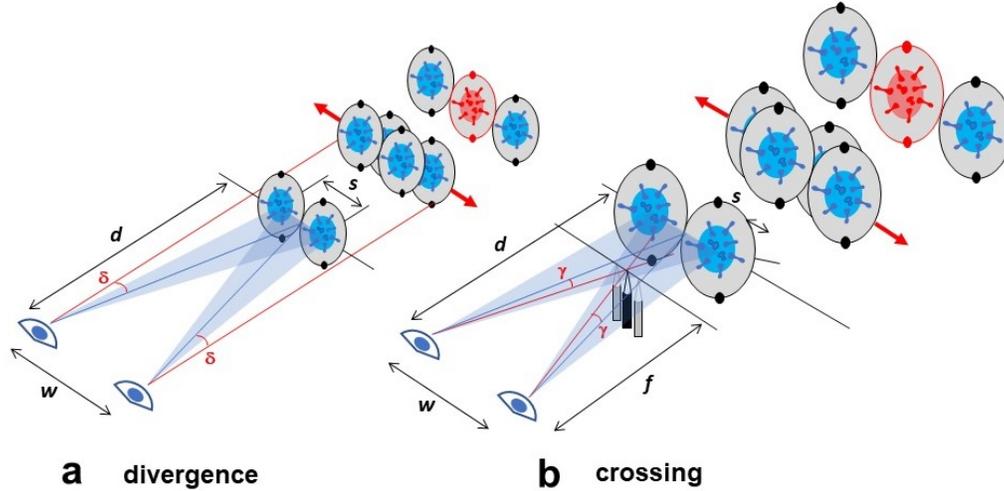


Figure 2: Two ways of viewing stereo pairs: (a) divergence of eyes and (b) crossing eyes. Blue rays represent "normal" view while red rays demonstrate how the viewing directions should be changed to provide 3D perception. Viewing beams for two eyes are shown by the red lines. In both viewing techniques, two images in a stereo pair are seen as a row of three images where the central image delivers stereo view.

$$\delta \approx \frac{w}{2d} \quad (1)$$

76 where d is a distance between a paper (monitor) and eyes and w is an inter-
 77 pupillary distance, which is 62-64 mm for humans in average. The maximal
 78 observable shift ν of an image when diverging eyes into the parallel view is

$$\nu \approx \delta d \quad (2)$$

79 As both the images must be shifted at $s/2$ towards each other, from
 80 (1) and (2) it follows that s should be less or equal to w . Therefore, the
 81 total width of a stereo pair can not be larger than $2w$. In other words, the
 82 divergence technique is only applicable for small images whose physical width
 83 does not exceed 120-130 mm. This is probably not as dramatic limitation in
 84 the era of smartphones, when images are often viewed at small screens.

85 For the crossing technique, the eyes viewing beams should be tilted in the
 86 other directions as shown in Fig 2. The observable shift can be deduced as:

$$\nu \approx (\gamma - \delta)d \quad (3)$$

87 where γ is defined by the minimal focal distance at which the observer can
 88 focus her/his eyes:

$$\gamma = \frac{w}{f} \quad (4)$$

89 As the observer is typically able to focus eyes at distance f compara-
 90 ble to interpupillary distance w , γ can reach one radian. This means that
 91 the crossing technique is applicable for the broad range of the image sizes in-
 92 cluding presentations at a large screen in an auditorium. However, a crossing
 93 view requires in general more training in comparison to a divergence view.
 94 We recommend the following step sequence:

- 95 1. Look normally at the stereo pair. Place a sharp tip of a pen or a pencil
 96 on the way of your view as shown in Fig 2b. As you are focused at the
 97 distant images, you will see two pencil tips at that moment.
- 98 2. Tune the position of the pencil such as the left tip points to the center
 99 of the left image in the stereo pair and the right tip points respectively
 100 to the center of the right one (Fig. 2b). If necessary, tilt the head a
 101 bit.
- 102 3. Focus your view at the pencil. Two tips merge in one. Note that the
 103 images at the back view now form a "trio". Try to tune the central
 104 image in the trio such as the marker points coincide precisely.
- 105 4. Carefully move you attention from the pencil tip to the central image
 106 *without* loosing the angle between both beams of sight. Remove the
 107 pencil.

108 The disadvantages of such stereo view comparing to tomographic recon-
 109 struction are quite clear. First, it allows to visualize about half of a 3D object
 110 only as the back side is invisible for both images in a stereo pair. Second,
 111 the depth scaling depends on the acquisition and viewing conditions. The
 112 accurate perception of the depth dimension is only achieved if

$$d = \frac{w}{\Delta\alpha} \quad (5)$$

113 where w is, as before, the interpupillary distance, d is the distance to the
 114 paper (monitor) and $\Delta\alpha$ is the change in the α tilt of two images. For the
 115 typical inspection distance of 250mm and $w = 62-64$ mm, this suggests that

116 best $\Delta\alpha$ is about 15° . When d deviates from (5), the perceived depth dimen-
117 sion would correspondingly deviate from the reality ¹. Still, these drawbacks
118 might be not as crucial taking into account the ease of image acquisition and
119 processing.

120 Furthermore, stereo view and tomographic reconstruction are not neces-
121 sarily competitive techniques. One of the questions of tomography is how
122 to display reconstructed objects in presentations [2]. Flat projections are
123 not quite informative while videos with rotating 3D objects are not always
124 technically possible. A couple of adequately chosen stereo views formed from
125 the tomographic reconstruction could be an effective solution.

126 Except of the practical utility of TEM stereo view, the exercises described
127 above might induce some general thoughts about 3D reconstruction. At
128 the moment when the stereo view at two images is successfully achieved,
129 the observer experiences a sudden and quite realistic 3D perception. This
130 perception has even a certain tolerance - the head can be slightly moved or
131 titled without immediate disappearance of the 3D perception. Of course, such
132 a "reconstruction in brain", as any reconstructions, is not free of artefacts
133 that in this case would be called optical illusions. Still, the reconstruction
134 is processed by the brain almost instantly while the accuracy based on only
135 two images is amazing [2]. Imitation of such performance by the existing
136 computer technologies typically results in a rather complicated and slow code
137 [8, 9]. The future of the image processing is commonly expected in developing
138 sophisticated artificial networks. In that respect, the deep examination of
139 how the visual reconstruction is actually processed in the natural networks
140 might be very instructive.

141 More examples of TEM stereo pairs can be found in Supplementary Ma-
142 terial. The open-source DigitalMicrograph plugin for making stereo pairs can
143 be free downloaded at <http://temdm.com/web/plugins/>.

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¹This disadvantage may eventually turn to an advantage for some objects where the negligible variation of features with depth needs to be artificially enhanced.

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152 **Supplementary**

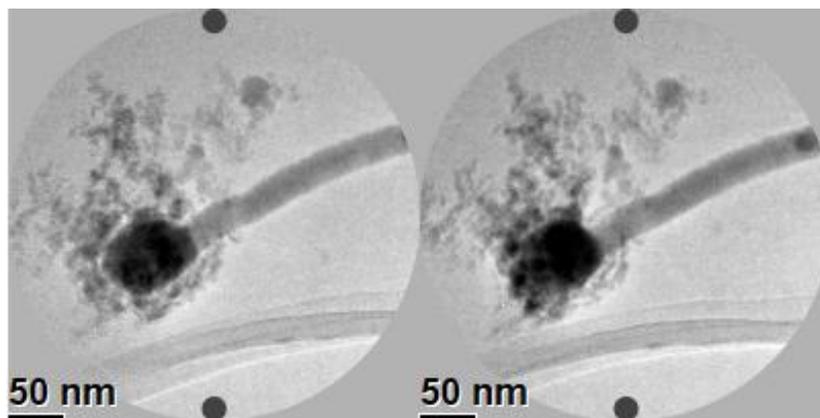


Figure 3: Stereo pair showing a BiRh nanowire growing from a round particle surrounded by the nebula of tiny stuff. The difference in α -tilt is 20.4° .

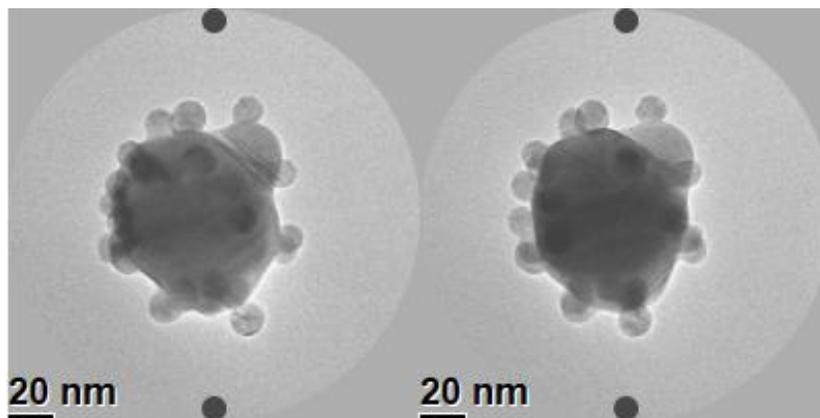


Figure 4: Stereo pair showing three connected Au particles decorated by smaller Au satellites. The difference in α -tilt is 14.8° .

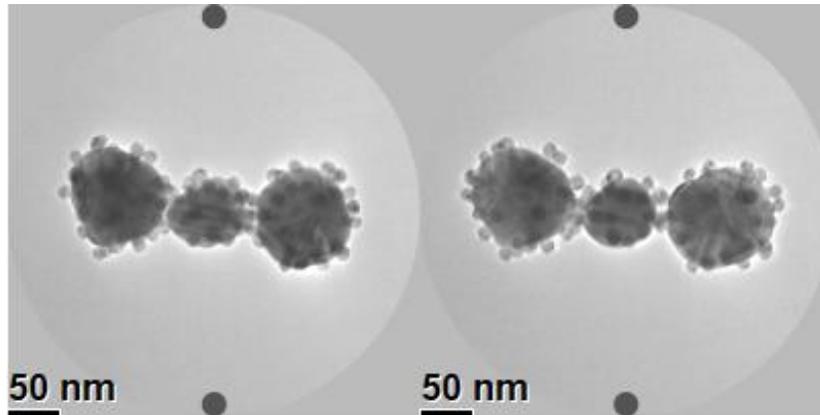


Figure 5: Stereo pair showing three connected Au particles decorated by smaller Au satellites. The difference in α -tilt is 19.5° .

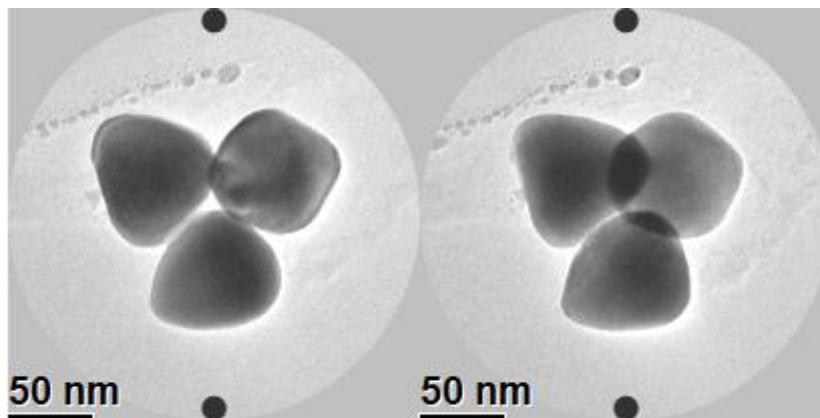


Figure 6: Stereo pair showing an agglomeration of three Au particles of nearly cubic shape. The difference in α -tilt is 22.0° .

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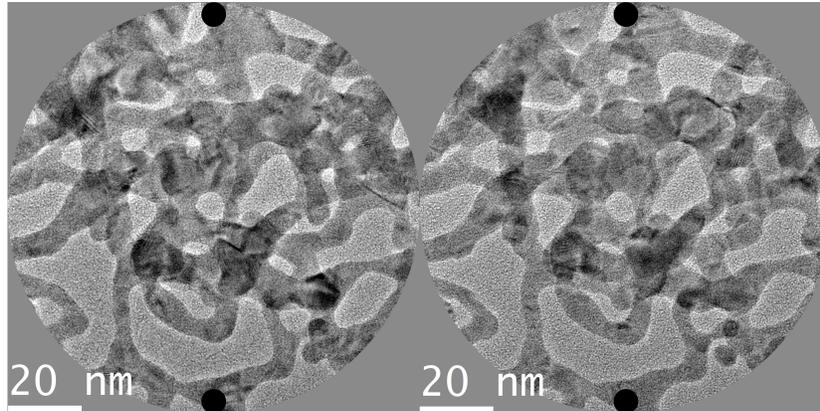


Figure 7: Stereo pair showing a debris of Au networks. The difference in α -tilt is 14.9° .

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